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### **# 400-006-2665**

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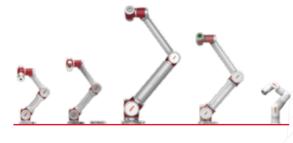
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**Global Leader in Flexible Intelligent Robotics** 



PRODUCT SELECTION GUIDE





## **No Teaching Pendant**

Programming JAKA collaborative robots is made easy with our JAKA APP, available for Android and Windows devices. Traditional teaching pendants are no longer necessary.



### **Wireless Connection**

Say goodbye to messy wires! JAKA cobots can now communicate and receive task assignments via their own WiFi connection, leaving you with a clean and safe workspace.



### **Graphic Programming**

Our intuitive graphic programming software interface is designed for anyone to use, regardless of prior programming experience. Setting positions and tasks is a breeze with our user-friendly interface.



# **Drag Teaching**

With our drag teaching function, users can deploy a cobot in just a few minutes. Simply move the cobot to any desired position, and it will instantly memorize it.



# **Safe Human-robot Collaboration**

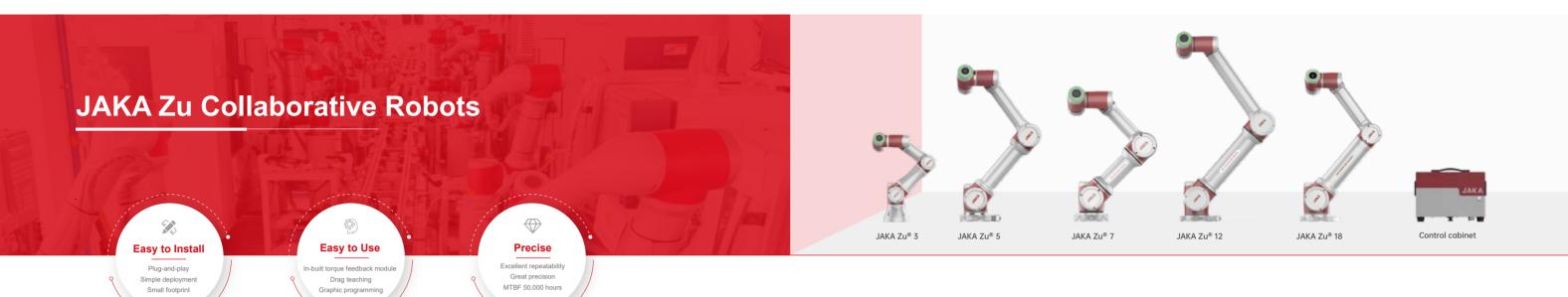
JAKA cobots are designed to work safely alongside humans, without the need for a safety fence, thanks to their collision detection module. Even the slightest bump can be detected, allowing the cobot to react and avoid causing harm.



# Plug-and-play

Install a JAKA cobot in just a few minutes, and mount it in any position or inclination. Our cobots are lightweight and are compatible with a wide range of grippers and end effectors. This makes them highly versatile and able to be deployed and re-deployed in any production environment.

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	Parameter	JAKA Zu <sup>®</sup> 3		JAKA Zu <sup>®</sup> 5		JAKA Zu <sup>®</sup> 7		JAKA Zu <sup>®</sup> 12		JAKA Zu <sup>®</sup> 18		
	Maximum payload	3	Bkg	5	kg	7	'kg	12	2kg	18kg		
	Weight	1:	12kg		23kg		22kg		41kg		35kg	
	Working radius	626mm		954mm		819mm		1327mm		1073mm		
Product features	Repeatability	±0.02mm		±0.02mm		±0.02mm		±0.03mm		±0.03mm		
	Number of axis		6	6			6	6		6		
	Programming	Drag teaching and	graphic programming	Drag teaching and	graphic programming	Drag teaching and	graphic programming	Drag teaching and	graphic programming	Drag teaching and graphic programming		
	Teaching pendant	PC, mobile	(PAD/mobile)	PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		
	Robot joint	Working range	Maximum speed	Working range	Maximum speed							
	Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s	
	Joint 2	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	120°/s	-85°,+265°	120°/s	
Working range	Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s	
and speed	Joint 4	-85°,+265°	220°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	
	Joint 5	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	
	Joint 6	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	
	Maximum speed of the tool end	1	1.5m/s	1	3m/s	1	2.5m/s	1	3m/s	1	3.5m/s	
	Power consumption	150W		350W		35	50W	50	00W	500	W	
	IP protection	IP54		IP54		IP54		IP54		IP54		
Specifications		2 Digital inputs		2 Digital inputs		2 Digital inputs		2 Digital inputs		2 Digital inputs		
Opecinications	Tool I/O ports	2 Digital outputs		2 Digital outputs								
		2 Analog input		2 Analog input		2 Analog input		2 Analog input		2 Analog input		
	Base diameter	129mm		158mm		158mm		188mm		188mm		
	IP protection	IF	P44	IP44		IP44		IP44		IP44		
	I/O ports	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		
Control ashingt	Communication	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		
Control cabinet	Power	100-240V	AC, 50-60Hz	100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		
	Size	410×307×235	5 mm (W×H×D)	410×307×235	mm (W×H×D)	410×307×235	5 mm (W×H×D)	410×307×235	5 mm (W×H×D)	410×307×235 i	mm (W×H×D)	
	Weight	13	.5kg	15.	4kg	15	.4kg	18	Bkg	18k	g	

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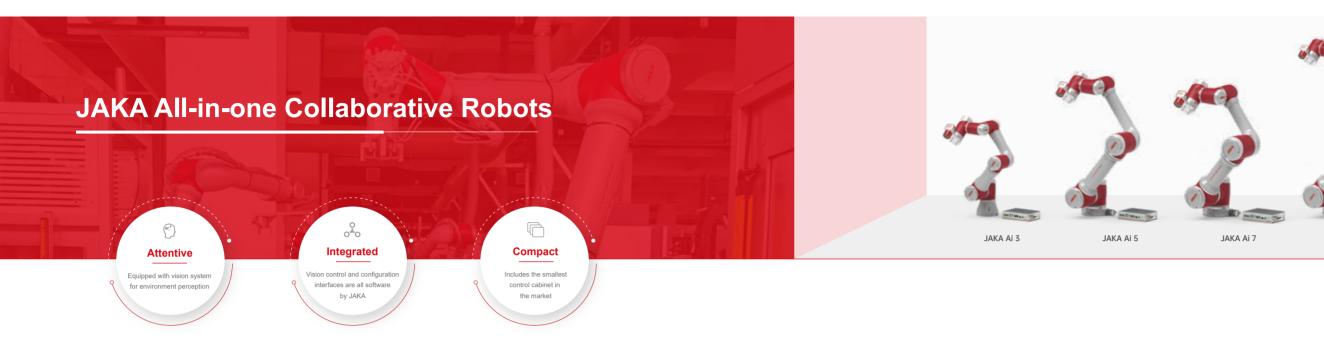


	Pa	arameters	JAKA	Zu <sup>®</sup> 3s	JAKA 2	Zu <sup>®</sup> 5s	JAKA	Zu® 7s	JAKA 2	Zu <sup>®</sup> 12s	JAKA 2	Ľu® 18s
	Max	kimum payload	3	ßkg	51	kg	7	kg	12	2kg	18kg	
		Weight	12kg		23kg		22kg		41kg		35kg	
	Working radius		626mm		954mm		819	9mm	132	7mm	107	3mm
Product features	F	Repeatability	±0.0	)2mm	±0.0	2mm	±0.0	2mm	±0.0	03mm	±0.0	3mm
	N	ımber of axis		6	(	6		6		6	6	
	Programming Teaching pendant		Drag teaching and	graphic programming	Drag teaching and g	graphic programming	Drag teaching and graphic programming		Drag teaching and	graphic programming	Drag teaching and graphic programming	
			PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile	(PAD/mobile)	PC, mobile	(PAD/mobile)	PC, mobile (PAD/mobile)	
		Robot joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
		Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s
		Joint 2	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	120°/s	-85°,+265°	120°/s
Working range		Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s
and speed		Joint 4	-85°,+265°	220°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s
	Joint 5		±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Joint 6		±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Maximum speed of the tool end		1	1.5m/s	1	3m/s	1	2.5m/s	1	3m/s	1	3.5m/s
	Power consumption		15	50W	350	0W	35	0W	50	WOO	50	OW
Specifications	IP protection		IP54		IP54		IP	254	IF	P54	IP	54
Specifications	Tool I/O ports		2 digital input, 2 digita	l output, 2 analog output	2 digital input, 2 digital	output, 2 analog output	2 digital input, 2 digital	output, 2 analog output	2 digital input, 2 digital	output, 2 analog output	2 digital input, 2 digital	output, 2 analog output
	Base diameter		12	9mm	158	Bmm	158	Bmm	188	3mm	188	mm
		Range (Fx/Fy)	100N/250N	200N/400N	100N/250N	200N/400N	100N/250N	200N/400N	250N	400N	250N	400N
	End tool	Interface type	Ethernet interface	Serial port	Ethernet interface	Serial port	Ethernet interface	Serial port	Ethernet interface	Serial port	Ethernet interface	Serial port
Force sensor		IP protection	IP64		IP64		IP64		IP64		IP64	
		Range (Fx/Fy)	500N		1600N		1600N		4000N		4000N	
parameters	Base	Interface type	Etherne	tinterface	Ethernet interface		Ethernet interface		Ethernet interface		Ethernet interface	
	Bass	Voltage	2	4V	24	4V	24V		24V		24V	
	IP protection		IF	964	IP64		IP64		IP64		IP64	
	ı	P protection	IF	P44	IP44		IP44		IP44		IP44	
		I/O ports	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs	
Ountral askinst	Co	mmunication	TCP/IP, Modbus TCP, Mod	bus RTU, Profinet, Ethernet/IP	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IF		P TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP	
Control cabinet		Power	100-240V	AC, 50-60Hz	100-240VA	AC, 50-60Hz	100-240VA	AC, 50-60Hz	100-240VA	AC, 50-60Hz	100-240VA	C, 50-60Hz
		Size	410×307×23	5 mm (W×H×D)	410×307×235	mm (W×H×D)	410×307×235	mm (W×H×D)	410×307×235	5 mm (W×H×D)	410×307×235	mm (W×H×D)
		Weight	13	.5kg	15.4kg		15.4kg		18kg		18kg	

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JAKA Ai 12

JAKA Ai 18



	Parameters	JAKA Ai 3		JAKA Ai 5		JAKA Ai 7		JAKA Ai 12		JAKA Ai 18	
	Maximum payload	3	Bkg	5	ikg	7kg		12kg		18kg	
	Weight	12	2kg	23	3kg	22kg		41kg		35kg	
Burdent frateur	Working radius	626mm		954mm		819mm		1327mm		1073mm	
Product features	Repeatability	±0.02mm		±0.02mm		±0.0	02mm	±0.0	03mm	±0.03mm	
	Number of axis	6		6			6	6		6	
	Programming	Drag teaching and graphic programming		Drag teaching and	Drag teaching and graphic programming		graphic programming	Drag teaching and	graphic programming	Drag teaching and graphic programming	
	Teaching pendant	PC, mobile (PAD/mobile)		PC, mobile	PC, mobile (PAD/mobile)		(PAD/mobile)	PC, mobile	(PAD/mobile)	PC, mobile (PAD/mobile)	
	Robot joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
	Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s
	Joint 2	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	120°/s	-85°,+265°	120°/s
Working range	Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s
and speed	Joint 4	-85°,+265°	220°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s
оппороси	Joint 5	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Joint 6	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Maximum speed of the tool end	1	1.5m/s	1	3m/s	1	2.5m/s	1	3m/s	1	3.5m/s
	Power consumption	150W		350W		350W		500W		50	00W
Specifications	IP protection	IP54		IP54		IP54		IF	P54	IF	P54
Specifications	Tool I/O ports	2 digital input, 2 digital output, 2 analog output		2 digital input, 2 digital output, 2 analog output		2 digital input, 2 digita	l output, 2 analog output	2 digital input, 2 digital output, 2 analog output		2 digital input, 2 digita	output, 2 analog output
	Base diameter	129mm		158mm		15	8mm	188mm		18	8mm
	Lens focal length	8mm	16mm	8mm	16mm	8mm	16mm	8mm	16mm	8mm	16mm
	Color mode	B&W	//Color	B&W/Color		B&W/Color		B&W/Color		B&W	//Color
	Vision	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm
JAKA Lens 2D	Precision	>0.08mm	>0.04mm	>0.08mm	>0.04mm	>0.08mm	>0.04mm	>0.08mm	>0.04mm	>0.08mm	>0.04mm
parameters	Communications interface	Ethernet interface	e (TCP/IP protocol)	Ethernet interface (TCP/IP protocol)		Ethernet interface (TCP/IP protocol)		Ethernet interface (TCP/IP protocol)		Ethernet interface (TCP/IP protocol)	
	Resolution	2592	2×1944	2592	2×1944	2592×1944		2592×1944		2592×1944	
	Frame rate	24	FPS	24	FPS	24FPS		24FPS		24FPS	
	Input power		DC	230-60V		DC30-60V					
	Input current		5	≤40A		≤40A					
MiniCab achinet	Size		180×28×47	17 mm (L×W×H)		180×28×47 mm (L×W×H)					
MiniCab cabinet	IP protection			IP20				IF	20		
	I/O ports		7-way port; Input a	nd output configurable				7-way port; Input ar	nd output configurable		
	Communication		TCP/IP, Modbus TCP, Mod	dbus RTU, Profinet, Etherne	et/IP		-	TCP/IP, Modbus TCP, Mod	bus RTU, Profinet, Ethernet/II	P	
	Weight		About 1.7 kg (inc	cluding accessories)		About 1.7 kg (including accessories)					

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	Parameters	JAKA	Pro 5	JAKA	Pro 12	JAKA	Pro 16		
	Maximum payload	5k	kg	1:	12kg		16kg		
	Weight	23.5kg		4	1kg	74kg			
Durchard fractions	Working radius	954mm		132	27mm	1713mm			
Product features	Repeatability	±0.02mm		±0.0	)2mm	±0.0	±0.03mm		
	Number of axis	6	6		6		6		
	Programming	Drag teaching and g	raphic programming	Drag teaching and	graphic programming	Drag teaching and	graphic programming		
	Teaching pendant	PC,Mobile device	ce (PAD/mobile)	PC,Mobile dev	ice (PAD/mobile)	PC,Mobile dev	ice (PAD/mobile)		
	Robot joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed		
	Joint 1	±360°	180°/s	±360°	120°/s	±360°	120°/s		
	Joint 2	-85°,+265°	180°/s	-85°,+265°	120°/s	-85°,+265°	120°/s		
Working range	Joint 3	±175°	180°/s	±175°	120°/s	±175°	120°/s		
and speed	Joint 4	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s		
	Joint 5	±360°	180°/s	±360°	180°/s	±360°	180°/s		
	Joint 6	±360°	180°/s	±360°	180°/s	±360°	180°/s		
	Maximum speed of the tool end	/	3m/s	I	3m/s	1	3.9m/s		
	Power consumption	Power consumption 350W		50	00W	75	50W		
	IP protection	IP68		IF	IP68		268		
Specifications		2 Digital inputs		2 Digit	al inputs	2 Digit	al inputs		
Specifications	Tool I/O ports	2 Digital outputs		2 Digita	2 Digital outputs		2 Digital outputs		
		2 Analog input		2 Analog input		2 Analog input			
	Base diameter	158	mm	188mm		246mm			
	IP protection	IP4	14	IP44		IP44			
	I/O ports	16 digital inputs, 16 digital outp	uts, 2 analog inputs or outputs	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs			
	Communication	TCP/IP, Modbus TCP, Modbu	us RTU, Profinet, Ethernet/IP	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP			
Control cabinet	Power	100-240VA	C, 50-60Hz	100-240VA	100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		
	Size	410×307×235	mm (W×H×D)	410×307×235	5 mm (W×H×D)	410×307×23	5 mm (W×H×D)		
	Weight	15.4	4kg	18	8kg	1	Bkg		

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## **JAKA Lens 2D**



#### **Product description**

The JAKA Lens 2D camera is equipped with a high-resolution industrial camera, a light source module, and an optional camera lens to provide our collaborative robots with machine vision capabilities. Despite its small and delicate appearance, this camera is highly effective. It can be installed either in a fixed position or at the end of the cobot.









#### Product Features **△**

### Integrated design

The 2D camera consists of three key components: a camera, a lens, and a light source. It is able to communicate with a JAKA robot control cabinet through the web, making it an easy-to-use and highly effective addition to our cobots.

### Easy operation

Our control cabinet is embedded with intelligent vision algorithms. Additionally, it features flexible communication interfaces that are able to adapt to the robot body, ensuring that it is a highly versatile and adaptable tool.

#### Scenario-adaptable

Our 2D camera also supports third-party camera extensions and custom external light sources, making it highly versatile and adaptable to a wide range of application scenarios.

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Parameters	Lens 2D CGC500-F08	Lens 2D CGC500-F16
Resolution	2592×1944	2592×1944
Max frame rate	24fps	24fps
Data interface	Gige	Gige
Color mode	Black and white / color	Black and white / color
Lens focal length	8mm	16mm
Object distance	>100mm	>100mm
Vision	>70×50mm	>35×25mm
Precision	>0.08mm	>0.04mm
Image processing	Soft-trigger image acquisition, single frame processing time within 1s	Soft-trigger image acquisition, single frame processing time within 1s



### **Product description ≥**

JAKA Lens VPS 2.0 is a cutting-edge technology that utilizes a high-performance AI-SoC chip, along with high-speed and large-capacity memory and storage. It is equipped with a high-performance acceleration engine, which can perform target detection, object recognition, human pose point extraction, and behavior understanding. The VPS is designed to be installed at the top of the cobot's working area, allowing the camera to monitor the behavior of inspected objects (both people and objects) in real time, ensuring the safety of both people and equipment. The camera also features a Gigabit Ethernet port, which supports data extraction and video visualization.





#### **Product Features ≥**



Built-in neural network accelerator for AI recognition and analysis of video



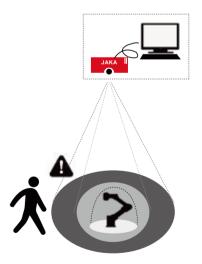
Event recording function, which can record key video segments, eliminate redundant information, trace back, and analyze more conveniently



Plug and play, no need to install software, access settings via browser



It can perform AI detection functions such as helmet wearing, personnel target tracking, personnel labor intensity, and video scoring calculation



Visual protection system working diagram

#### Basic parameters

Hardware platform	CMOS camera, embedded system, DSP, AI engine, etc.			
Dimensions	101.7×72×51.1mm			
Installation method	Directly above, sideways (suggested install at 45°)			
Communication interface	Ethernet interface, RS485, PNP optocoupler isolation DI and DO			

### Visual parameters

8.3 MP
200 ms
≥2.5 m (suggested)
4 m x 2.1 m (adjustable)

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# **JAKA MiniCobo**

### **Product introduction**

The JAKA MiniCobo is a small, rounded robot that is perfect for applications where appearance is important. Thanks to its built-in communication port, it doesn't require any external cables and can be easily connected to any tool that is compatible with JAKA. Additionally, JAKA's MiniCobo incorporates intelligent control algorithms, giving it a superior performance compared to its competitors. The MiniCobo operates quietly, making it an ideal solution for a range of industries including hospitality, education, retail, services, and entertainment, among others.











9.4kg



1.0kg

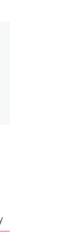






Working radius Repeatability

±0.1mm

















	Parameter	MiniCobo				
	Payload	1kg				
	Weight	9.4kg				
	Work radius	580mm				
Product features	Repeatability	±0.1mm				
	Axis	6 a.	xes			
	Programming	Graphical program	mming, free-drive			
	Teach pendant	MT (Pad/M	lobile) App			
	Collaborative operation	Accordance with	GB 11291.1-2011			
	Robot joint	Working range	Maximum speed			
	Joint1	±360°	180°/s			
	Joint2	±120°	180°/s			
Working range	Joint3	±130°	180°/s			
and speed	Joint4	±360°	180°/s			
	Joint5	±120°	180°/s			
	Joint6	±360°	180°/s			
	Maximum speed of the tool end	1	1.5m/s			
	Rated power	150W				
	Temperature range	0-50°C				
	IP Protection	IP.	40			
	Installation	At any	angle			
		2 Digital inputs				
Specifications	Tool I/O	2 Digital outputs				
Specifications		2 Analog input				
	Tool I/O power	24V	/DC			
	Tool I/O size	M8				
	Materials	Aluminum, PC				
	Base diameter	124mm				
	Cable length	6m				
	Power input	20-60VDC				
	Current	0-11.67A				
	Size	180×128×47 mm (L×W×H)				
	IP Protection	IP20				
MiniCab cabinet	I/O	7 Digital input: I/O configurable				
Willicab Cabillet	I/O Power	24VDC				
	Installation	Panel/Guide Rail				
	Communication	TCP/IP, Modbus TCP, Modbu	s RTU, Profinet, Ethernet/IP			
	Weight	1.1kg				
	Material	Alumminum, Steel				

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